

Thanks for purchasing the Tinyhawk III. Please follow the instruction manual to assemble and configure your Tinyhawk III.

Design in California, Made in China

Disclaimer

1. Please read the disclaimer carefully before using this product.

2. By using this product, you hereby agree to this disclaimer and signify that you have read them carefully and completely.

3. This product is not suitable for people under the age of 18. Adult supervision is highly recommended for kids under the age of 18.

4.Our Tinyhawk features open-source flight controller and Electronic Speed Controllers to meet the FPV enthusiasts' need to upgrade their quad. Please read the instruction manual and warnings carefully.

5.Before every flight, make sure the battery is fully charged and power connections are secure.

6. DO NOT fly around crowds, children, animals or objects.

7. EMAX ACCEPTS NO LIABILITY FOR DAMAGE(S) OR INJURIES INCURRED DIRECTLY OR INDIRECTLY FROM THE USE OF THIS PRODUCT.

Precautions

1.Please follow the instructions to assemble and to operate this product correctly.

2. Do not use this product if you have physical or mental illness, dizziness, fatigued, or use while under the influence of alcohol or drugs.

3. Please fly in a safe area away from people

4. Do not modify or use other parts and accessories not approved for the use of EMAX.

5. Do not use this product in harsh environments (such as winds, rain, lightning, snow, etc.).

6. Do not use this product in a strong electromagnetic environment.

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Product specification

Size and weight			
Diagonal Wheelbase	76mm		
(Without propeller)			
Maximum size of Drone			
(Without propeller)			
Drone weight	220		
(Without battery)	529		
Motor	TH0802 II 15000KV		
Propeller	Avia TH Propeller		
	F4 (STM32F411 firmware)		
Main board	4in1 5A ESC		
	EMAX Tiny receiver (SPI receive mode, Frsky D8)		
Camera	RunCam Nano 4 Camera		
VTY	200-100-25MW adjustable frequency 37CH,		
VIA	support SmartAudio		
Battery	1S HV 450mAh		

Product list

Tinyhawk III	× 1
Emax 1s HV 450 mAh	×1
Charger	×1
Propeller	(2XCW, 2XCCW)
Spareparts	x 1

Tinyhawk III propeller

Tinyhawk III structure diagram



Propeller installation & removal

The Tinyhawk III propeller has two directions of rotation: clockwise (CW) and counterclockwise (CCW). When purchasing a set of propellers, please purchase 2 clockwise blades and 2 counterclockwise blades. The blade rotates along the blunt edge of the blade. When installing the propeller blade, please install it in the correct direction of the propeller blade as shown in the figure below.



Propeller installation

Align the 3 shafts of the propeller with the 3 shafts of the motor, supporting the back of the motor, then press the blade in by hand until it is flush with the motor shaft.

Note: If the propeller is installed incorrectly, the Tinyhawk III cannot fly normally and cannot be controlled. Please carefully check whether the propeller is in the correct direction; if there is no support on the back of the motor, it may cause the frame to break; pay attention to safety when installing the propeller.

Propeller disassembly

Use a small tool (such as a 1.5mm hex wrench or a small screwdriver) to press on the metal at the bottom of the motor and Tinyhawk III. Grasp the blade of the propeller with your fingers until the propeller pops out of the motor.

Note: It is only necessary to disassemble the propeller when replacing a new propeller; pay attention to safety when dismantling the propeller and when using tools.

Tinyhawk VTX Settings

Vtx Schematic and Button Diagram



Changing VTX setting via Betaflight OSD

Tinyhawk III is equipped with SmartAudio and is already configured with stock settings. The SmartAudio line is operated on UART 2 TX.

Follow the prompts on the screen to enter the main setting menu. The throttle is in the middle, the direction is to the left, and the pitch is up (THROTTLE MID+ YAW LEFT+ PITCH UP) to enter the OSD parameter adjustment menu, as shown in **Figure 1**.

In the menu interface, switch the pitch up/down (PITCH) and select the menu option. Move the cursor to "FEATURES" and stir the ROLL lever to the right to enter the next menu. as shown in **Figure 2**. Use the PITCH joystick to move the cursor to "VTX SA", as shown in **Figure 3**. Then pull the roll (ROLL) lever to the right to enter the VTX configuration menu.as shown in **figure4**.

In the menu of VTX SA, we can configure BAND, CHAN and POWER. Pull the PITCH lever to move the cursor up and down to select the VTX option that needs to be set. Once the parameters are set, move the cursor to "SET", then turn the joystick to the right, enter "SET" and select "YES", turn the joystick to the right to save the set parameters, as shown in **Figure 5**.

In the VTX SA menu, move the cursor to "CONFIG" to enter the menu; move the cursor to "PIT FMODE" and pull the ROLL lever to the right to turn off the VTX power supply.as shown in **figure6**.



Figure 1

Figure 2





Figure 4





Figure 6

Press the key to set the VTX channel

Note: You must "disable" the VTX Smart Audio on UART 2 in order for the push-button VTX adjustment to work as described below.

BETAP Configurator 10 Firmware: 5°FL4 Target: MAI EKF4	ELIGHT 5.1 116x	 ▲ ♥	0.01 V Ø Gy	8 🙏 🕅 💩	No datafiest chip found GPS Sonar	Mode Update Disconnect
2019-09-09 @ 16:34:39 Armin	g Disabled					Show Log
	Dente					
🖆 Ports	Ports					WIKI
Configuration	Note: not all	combinations are valid. When	n the flight contr	oller firmware detects this the se	rial port configuration will be reset.	renfin antion if you do
🖾 Power & Battery	Note. Do NO	Tuiseble war off the first set	ter por curress y	ou know what you are doing. Tou	may have to renas rand erase your	chingaractor in you do.
க் PID Tuning	Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Pcripherals
🛓 Receiver	USB VCP	115200 🗘		Disabled \$ AUTO \$	Disabled \$ AUTO \$	Disabled AUTO
🖀 Mades	UART1	115200 \$		Disabled \$ AUTO \$	Disabled ; AUTO ;	Disabled + AUTO +
🛓 Motors	UART2	115200 \$		Disabled \$ AUTO \$	Disabled 4 AUTO 4	Disabled + AUTO +
						1

Normal display

All LEDs on the VTX are normally off until the button is pressed. To check band and channel status click the button once quickly, and LED starts to indicate frequency band and frequency channel. First indicate the frequency band and then indicate the frequency channel. After both 2 rounds of LED display cycles, all LEDs will turn off.

Press and hold the button for 5 seconds to enter the menu. After entering the menu, the band LED lights up.

Press the button again for 5 seconds to save the parameters and exit the menu. After saving and exiting the menu, all LED indicators are off.

Menu Entry / Exit

(1)Press the button and hold for 5s to enter the menu. After entering the menu, BAND LED lights up.

(2)Press the button and hold for 5s again to save parameters and exit the menu. After saving and exiting the menu, all LED goes out.

Band and Channel parameter change

After entering menu, short click button to switch frequency group band(b)/frequency channel (C),and the LED of the corresponding menu is lit.

Enter/Exit Parameters

After choosing menu, press the button and hold for 2s to enter parameter option. **Notice:** If you use SmartAudio to switch to an illegal channel, Tinyhawk III will not have video transmission. To switch back to a legal channel, press the button on vtx and follow the vtx menu guide shown below.



Hold the VTX button while powering on drone to lock/unlock the VTX



Default ≤ 25mW Output)

FRCH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8	
А	5865	5845	5825	5805	5785	5765	5745	-	MHz
В	5733	5752	5771	5790	5809	5828	5847	5866	MHz
Е	—	-	Т	—		—	—	—	MHZ
F	5740	5760	5780	5800	5820	5840	5860	—	MHz
R	—		-	5769	5806	5843	-		MHz

FCC: Ham radio license is required for use in North America.

EU/CE: The frequency is restricted to prevent transmission outside the specified CE frequency.

FRCH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8	
А	5865	5845	5825	5805	5785	5765	5745	5725	MHz
В	5733	5752	5771	5790	5809	5828	5847	5866	MHz
Е	5705	5685	5665	-	5885	5905	-	—	MHz
F	5740	5760	5780	5800	5820	5840	5860	5880	MHz
R	5658	5695	5732	5769	5806	5843	5880	5917	MHz

Unlock configuration

FCC: Ham radio license is required for use in the USA. EU/Europe: Do not use unlock configuration.

E-band channels 4, 7, and 8 are restricted to prevent transmission outside the designated amateur radio frequencies. Adjustable video output power is only applicable to specific models.

* When the user purchases this product, it means that he/she understands these responsibilities and will operate the equipment legally. EMAX does not assume any responsibility for the user's purchase and/or use of this product in violation of government regulations.

BETAFLI Configurator: 10.5.1 Hrriware: BTFL 4.0.4 Target: MATERFATTRX	IGHT) 201 V ▲ ♥ ∂	X Gyro	Accel	A R Mag	Baro	Senar	No datafirsh chip found Enable Expert Node	Update Firmware	Disconnect
2019-09-09 @ 12:28:52 Arming Dis	abled									
📌 Setup	0 ; FPV Camera Angle [Cegrees]									
🖌 Ports										
Configuration	Receiver				R	SSI (Sign	al Strength)			0
Power & Battery	SPI RX support +	Receiver Mode			0		RSSLADC An	alog RSSI Input		
🚓 FID Tuning	Note: The SPLRX provider will only work if the	e required bardware is	on board	or						
d Receiver	connected to an SPI bus.									
a Modes	FRSKY_D ÷	SPI Bus Receiver Provi	der							

Binding Procedure

Binding is the process of uniquely associating a particular receiver to a transmitter module. A transmitter

module can be bound to multiple receivers (not to be used simultaneously). A receiver can only be bound to one transmitter module.

1.Hold the bind button while powering on the receiver. When the BLUE LED is on, it means the receiver is in BIND MODE

2.Turn on the transmitter, make sure it is set to D8 mode, and then set it into bind status. When the BLUE LED of the receiver starts flashing, it means bind successful.

3.Turn on the transmitter again, the BLUE LED receiver will be on, it means the receiver is receiving data from transmitter. Transmitter bind with receiver no need repetitive operation, unless you change either receiver or transmitter.

The receiver can be instructed to enter the binding mode through the Betaflight configurator. Type the following command in the CLI tab: bind_rx Click the Enter key, your receiver will enter the binding mode, and then follow the binding steps 2 and 3 to complete the binding process.

Tinyhawk III Flight Control Diagram



This flight controller has a MCU(STM32F411CEU6) with a MPU6000 gyro. Tinyhawk III flight controller comes pre-programmed and properly tuned for optimal flight. For a full tune and configuration setting file (CLI dump file) please visit https://emax-usa.com/ for the CLI dump file.

Stock Flight Controller Settings

PID profile 1 is tuned and optimized for Tinyhawk III and Emax 1S HV 450 mAh for proper flight indoors and outdoors. Please do not change these values.

This configuration has been professionally adjusted by many parties, and EMAX strongly recommends not to change these values arbitrarily.



Adjusting Software Settings (Betaflight Configurator)

Betaflight Configurator can be used to changed programmed settings on Tinyhawk III. Betaflight Configurator and flight controller firmware can be downloaded at https://github.com/betaflight/. The hardware target for Tinyhawk Flight Controller is MatekF411

DISCLAIMER:

We do not suggest changing any PID settings on TinyhawkIII or upgrading the firmware to new versions. Tinyhawk III comes stock with an optimal tune for proper flight performance. Changing this can affect flight time, overall speed, control of the aircraft, and excessive heat within the motors.

Reprogramming Tinyhawk Flight Controller

Put the Flight Controller in DFU mode by pressing the BOOT button while plugging in the micro USB cable to a computer. Select STM32F411 as the target and then select the firmware . Select Manual Baud Rate with 256000 in the drop down menu Select Load Firmware(Online) to download the firmware Select Flash Firmware to program the flight controller

Set the Correct Settings

Download the latest CLI Dump File from https://emax-usa.com/ Connect Tinyhawk to Betaflight configurator and select the CLI tab Open the CLI Dump File in a text editor and copy all the text. Paste the settings into the command bar and press enter Tinyhawk III will reconnect to Betaflight when completed



How To Fly Tinyhawk III

Before turning on the drone, please learn the controls first, and then turn on the drone. Be cautious when flying and operate in an open and controllable area. (Take EMAX's E8 Transmitter and Transporter 2 Goggles as examples).

First turn on the power of E8 Transmitter and Transporter 2. Tinyhawk III has been bound to E8 Transmitter and matched with your Transporter 2 on the correct video channel. Turn on your Tinyhawk III by sliding the battery into the battery tray and plugging in the power source. After the battery is inserted, place the Tinyhawk III on a level and stable surface so that it can be calibrated.

Calibration takes a few seconds, and then Tinyhawk III can fly. Tinyhawk III can fly for up to 4 minutes when the battery is fully charged. When the battery power reaches 3.2v, please land the Tinyhawk III; flying longer will seriously damage your battery and is not recommended.



Unlock



Arming refers to setting Tinyhawk III to begin flying. When Tinyhawk III is powered on for the first time, it will not spin the propeller until it is armed.

1. First move the throttle to the bottom position to control the aircraft,

2. Then move the left switch of the E8 Transmitter to the third position.

When Tinyhawk III is successfully armed, you will see the propellers spinning.

Note: In the event of a collision, Tinyhawk III must stop flying immediately. Failure to stop the flight in time will damage Tinyhawk III. Before handling Tinyhawk III, be sure to switch the switch to an unarmed position.

Flight



The AUX 2 switch is set as a 3-level switch to change this mode. When AUX 2 is in the first position, Tinyhawk III will be in Angle Mode and stabilize the aircraft. When the switch is in the middle 2nd position, Tinyhawk III will be in Horizon Mode, allowing the drone to perform acrobatics by tilting roll or pitch all the way to the end. The third position is Rate Mode which will turn off Gyro Stablization which is recommended for experienced pilots who wish to perform acrobatics and professional maneuvers.

1.Beginner Mode (Angle Mode): The maximum angle of Tinyhawk III is limited during flight to help limit speed and make flying easier. In this mode, the control of the aircraft is based on attitude. The pitch and roll input from the remote control controls the pitch and roll angle of the aircraft. For example, a 20-degree tilt of the joystick will be converted into a 20-degree tilt of the Tinyhawk III.

2. Intermediate mode (Horizon Mode): This mode has a higher angle limit and is used for higher speed flight with the same attitude control. The only difference is that at the end of the gimbal for pitch and roll, it will cause the aircraft to flip in that direction.

3. Advanced mode (Rate Mode): This mode allows you to fully control the aircraft. There are no more angle restrictions, and control is based on rate. This means that the control input from the joystick sets a rotation rate on the axis.

Straight Flight

To learn how to fly Tinyhawk III, you must first fly within sight (without wearing Transporter 2 Goggles). Turn on the power of Tinyhawk III and place it in a safe and empty room. Start Tinyhawk III, then use the left stick to raise the throttle to the hovering position. First try to maintain a stable altitude, the left and right thumbs control the throttle pitch angle of the joystick, so that the Tinyhawk III can fly normally. You need to practice many times until you have reached a level of proficiency.

Advanced Flight-First Person View (FPV) Flight

After you have certain basic operating skills, you can try to fly with the Transporter 2. Make sure that the Tinyhawk III and Transporter 2 goggles are on the same VTX channel, choose an open and safe place to fly, and operate according to your experience. Control the throttle to keep the aircraft level and fly slowly, which makes it easier to learn to fly FPV. When you have enough flying experience, you can control Tinyhawk III freely in the air.

The Transporter 2 screen display (OSD) image data from the Tinyhawk III camera. OSD displays important information such as flight time and battery voltage. During the flight, please always pay attention to these numbers to understand the remaining battery time. Tinyhawk III can fly up to 4 minutes. When the battery reaches 3.2v, let Tinyhawk III land. It is not recommended that the battery voltage be below 3.2v, otherwise the battery will be damaged.

Warning:

Try to maintain a controllable altitude flight. Do not slam the joystick when controlling Tinyhawk III, as this will make the aircraft difficult to control; do not let the battery be lower than 3.2v; when the default AUX3 switch is set to the second position (middle), A buzzer will be activated to find Tinyhawk III.

Thank you for purchasing our product!

Enjoy your flight with EMAX.



Warning:

<u>REMINDER! Please pay attention to safety of your surrounding. Not</u> <u>Recommended for persons under 18 years of age!</u>

